

# Asmt 6: Graphs

Turn in through Canvas by 5pm:

Wednesday, April 29

10 points (but you can earn up to 20 points)

This is optional, and will be averaged into your grade **only** if it improves your grade

## Overview

In this assignment you will explore different approaches to analyzing Markov chains.

You will use two data sets for this assignment:

- <http://www.cs.utah.edu/~jeffp/teaching/cs5140/A6/M.dat>
- <http://www.cs.utah.edu/~jeffp/teaching/cs5140/A6/L.dat>

These data sets are in matrix format and can be loaded into MATLAB or OCTAVE. By calling

`load filename` (for instance `load M.dat`)

it will put in memory the the data in the file, for instance in the above example the matrix  $M$ . You can then display this matrix by typing

`M`

*As usual, it is highly recommended that you use LaTeX for this assignment. If you do not, you may lose points if your assignment is difficult to read or hard to follow. Find a sample form in this directory: <http://www.cs.utah.edu/~jeffp/teaching/latex/>*

## 1 Finding $q_*$ (10 points)

We will consider four ways to find  $q_* = M^t q_0$  as  $t \rightarrow \infty$ .

**Matrix Power:** Choose some large enough value  $t$ , and create  $M^t$ . Then apply  $q_* = (M^t)q_0$ . There are two ways to create  $M^t$ , first we can just let  $M^{i+1} = M^i * M$ , repeating this process  $t - 1$  times. Alternatively, (for simplicity assume  $t$  is a power of 2), then in  $\log_2 t$  steps create  $M^{2^i} = M^i * M^i$ .

**State Propagation:** Iterate  $q_{i+1} = M * q_i$  for some large enough number  $t$  iterations.

**Random Walk:** Starting with a fixed state  $q_0 = [00 \dots 1 \dots 00]^T$  where there is only a 1 at the  $i$ th entry, and then transition to a new state with only a 1 in the  $i'$ th entry by choosing a new location proportional to the values in the  $i$ th column of  $M$ . Iterate this some large number  $t_0$  of steps to get state  $q'_0$ . (This is the *burn in period*.)

Now make  $t$  new step starting at  $q'_0$  and record the location after each step. Keep track of how many times you have recorded each location and estimate  $q_*$  as the normalized version (recall  $\|q_*\|_1 = 1$ ) of the vector of these counts.

**Eigen-Analysis:** Compute `eig(M)` and take the first eigenvector after it has been normalized.

**A (4 points):** Run each method (with  $t = 512$ ,  $q_0 = [100 \dots 0]^T$  and  $t_0 = 50$  when needed) and report the answers.

**B (2 points):** Rerun the Matrix Power and State Propagation techniques with  $q_0 = [0.1, 0.1, \dots, 0.1]^T$ . For what value of  $t$  is required to get as close to the true answer as the older initial state?

**C (4 points):** Explain at least one **Pro** and one **Con** of each approach. The **Pro** should explain a situation when it is the best option to use. The **Con** should explain why another approach may be better for some situation.

## 2 BONUS 1: Taxation (4 points)

Repeat the trials in part **1.A** above using taxation  $\beta = 0.9$  so at each step, with probability  $1 - \beta$ , any state jumps to a random node. It is useful to see how the outcome changes with respect to the results from Question 1. Recall that this output is the *PageRank* vector of the graph represented by  $M$ .

Briefly explain (no more than 2 sentences) what you needed to do in order to alter the process in question 1 to apply this taxation.

## 3 BONUS 2: Graph Sparsification (6 points)

**A (3 points):** Consider the adjacency matrix  $L$ . Run the basic graph sparsification algorithm in **L26.1** with  $t = 2$ . Report the new matrix representing the graph.

**B (3 points):** Explain how clustering on the new graph may differ from that on the old graph. What problems may occur? Would these persist on a large graph with a large value of  $t$ , and Why?